Variable zuweisen

```python
# Import motor controls
pin_12 = 75
```

Motorsteuerung

```python
# Import motor controls
import mab_car as car

car.set_speed(1000)
car.forward()
time.sleep(1)
car.stop()
```

Benutzen des Timers

```python
# Import timer functionality
import time

# Use the timer to wait for half a second
time.sleep(0.5)

# Use the timer to measure time
start = time.time() # Store the current time in variable "start"
time.sleep(1) # wait for a second
end = time.time() # Store the current time in variable "end"
print(end - start) # Print the elapsed time
```